2-hour test in 01006 Advanced Engineering Mathematics May 11 2022

shsp 10.5.22

Problem 1

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> restart: with(LinearAlgebra):
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About a function $f: \mathbb{R}^2 \rightarrow \mathbb{R}$ it is given that the two first-order partial derivatives are > fx:=6*x-6*y

$$fx \coloneqq 6 x - 6 y \tag{1.1}$$

and

> fy:=6*y^2-6*x

$$fy := 6 y^2 - 6 x \tag{1.2}$$

Question 1

 $\nabla f(x, y) = (f'_x(x, y), f'_y(x, y)) = (6x - 6y, 6y^2 - 6x) = (0, 0)$ 6x - 6y = 0 and $6y^2 - 6x = 0$ x = y and y(y - 1) = 0 y = 0 and x = 0 or y = 1 and x = 1. All stationary points for f are then (0, 0) and (1, 1).

Question 2

The 2nd-order partial derivatives of f are > fxx:=diff(fx,x);fxy:=diff(fx,y);fyy:=diff(fy,y); fxx := 6 fxy := -6fyy := 12 y(1.2.1)

The Hessian matrix of f at point (x, y) is > $H(x, y) := \langle fxx, fxy; fxy, fyy \rangle$

$$H(x, y) := \begin{bmatrix} 6 & -6 \\ -6 & 12 y \end{bmatrix}$$
(1.2.2)

If f has local extremum at a point then that point must be a stationary point since f has no exceptional points.

> H(0,0) := subs(x=0,y=0,H(x,y))

$$H(0,0) := \begin{bmatrix} 6 & -6 \\ -6 & 0 \end{bmatrix}$$
(1.2.3)

(1.2.4)

> Eigenvalues (H(0,0), output=list) $[3+3\sqrt{5}, 3-3\sqrt{5}]$

As the two eigenvalues of H(0, 0) have opposite signs, we can conclude that f has neither local maximum nor local minimum in the stationary point (0, 0).

> H(1,1):=subs(x=1,y=1,H(x,y))

$$H(1,1) := \begin{bmatrix} 6 & -6 \\ -6 & 12 \end{bmatrix}$$
(1.2.5)

> Eigenvalues(H(1,1),output=list)

$$[9+3\sqrt{5},9-3\sqrt{5}]$$
 (1.2.6)

As both eigenvalues of H(1, 1) are positive, we can conclude that f has a proper local minimum in the stationary point (1, 1).

Question 3

It is now given that f(0, 0) = 1. The approximating 2nd-degree polynomial of f with expansion point (0, 0) is $P_2(x, y) =$

$$f(0,0) + f'_{x}(0,0)x + f'_{y}(0,0)y + \frac{1}{2}f''_{xx}(0,0)x^{2} + f''_{xy}(0,0)xy + \frac{1}{2}f''_{yy}(0,0)y^{2} = 1 + 3x^{2} - 6xy.$$

Problem 2

```
> restart:
with(plots):
prik:=(x,y)->VectorCalculus[DotProduct](x,y):
kryds:=(x,y)->convert(VectorCalculus[CrossProduct](x,y),Vector):
`vekdif`:=proc(X,Y) convert(diff(convert(X,list),Y),Vector) end
proc:
`vop`:=proc(X) op(convert(X,list)) end proc:
```

A function $h : \mathbb{R}^2 \rightarrow \mathbb{R}$ is given by the expression > $h := (x, y) - 2 \times x - y + 1$

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h \coloneqq (x, y) \mapsto 2 \cdot x - y + 1
```

(2.1)

The rectangle M_1 is located in the (x, y) place in (x, y, z) space and is given by $M_1 = \{(x, y) \mid 0 \le x \le 2, 0 \le y \le 1\}.$

Let G_1 denote the part of the graph of h that is located vertically above M_1 .

Question 1

A parametric representation of G_1 is

>
$$\mathbf{r}:= (\mathbf{u}, \mathbf{v}) \rightarrow \langle \mathbf{u}, \mathbf{v}, 2 \star \mathbf{u} - \mathbf{v} + 1 \rangle$$
:
> $\mathbf{r} (\mathbf{u}, \mathbf{v})$

$$\begin{bmatrix} u \\ v \\ 2u - v + 1 \end{bmatrix}$$
(2.1.1)

where $u \in [0; 2]$ and $v \in [0; 1]$. The normal vector of the surface is > N:=kryds(diff(r(u,v),u),diff(r(u,v),v))

$$N := \begin{bmatrix} -2\\ 1\\ 1 \end{bmatrix}$$
(2.1.2)

The corresponding Jacobian function is > Jacobian:=sqrt(prik(N,N))

$$Jacobian := \sqrt{6}$$
(2.1.3)

Ar(G₁) = $\int_{G_1} 1 \, d\mu = \int_0^1 \int_0^2 Jacobian(u, v) du \, dv = \int_0^1 \int_0^2 \sqrt{6} \, du \, dv = 2\sqrt{6}$.

The straight line segment between the points (0, 1) and (2, 0) divide M_1 in to parts. Let M_2 denote the lower part and let G_2 denote the part of the graph of *h* that is located vertically above M_2 .

Question 2

The straight line segment between the points (0, 1) and (2, 0) has the equation $y = 1 - \frac{x}{2}$.

A parametric representation of M_2 is then

$$\mathbf{r}(u, v) = (u, 0) + v(0, 1 - \frac{u}{2}) = (u, v(1 - \frac{u}{2}), \text{ where } u \in [0; 2] \text{ and } v \in [0; 1].$$

From this we construct the following parametric representation of G_2

> r:=(u,v)-><u,v*(1-u/2),2*u-v*(1-u/2)+1>:
> r(u,v)

$$\begin{bmatrix} u \\ v\left(1-\frac{u}{2}\right) \\ 2 u - v\left(1-\frac{u}{2}\right) + 1 \end{bmatrix}$$
(2.2.1)

where $u \in [0; 2]$ and $v \in [0; 1]$.

The normal vector of the surface is

> N:=simplify(kryds(diff(r(u,v),u),diff(r(u,v),v)))

$$N := \begin{bmatrix} -2 + u \\ 1 - \frac{u}{2} \\ 1 - \frac{u}{2} \end{bmatrix}$$
(2.2.2)

The corresponding Jacobian function is

> Jacobian:=sqrt(prik(N,N)) assuming -2+u<0

$$Jacobian := \frac{\sqrt{6} (2-u)}{2}$$
 (2.2.3)

Question 3

Let *f* be given by > f:=(x,y,z)->x+y+z-1: > f(x,y,z)

$$x + y + z - 1$$
 (2.3.1)

here $(x, y, z) \in \mathbb{R}^3$. The wanted surface integral is

$$\int_{G_{\mathbf{x}}} f \,\mathrm{d}\boldsymbol{\mu} = \int_{0}^{1} \int_{0}^{2} f(\mathbf{r}(u, v)) \,\mathrm{Jacobi}(u, v) \,\mathrm{d}u \,\mathrm{d}v$$

> integrand:=f(vop(r(u,v)))*Jacobian

integrand :=
$$\frac{3 u \sqrt{6} (2 - u)}{2}$$
 (2.3.2)

> Int(Int(integrand,u=0..2),v=0..1)=int(int(integrand,u=0..2),v=0. .1)

$$\int_{0}^{1} \int_{0}^{2} \frac{3 u \sqrt{6} (2 - u)}{2} du dv = 2\sqrt{6}$$
 (2.3.3)

Problem 3

> restart:with(LinearAlgebra):with(plots):

A solid body L in (x, y, z) space is given by the parametric representation

> $r:=(u,v,w) \rightarrow v^{u^{2}\cos(w)}, v^{u^{2}\sin(w)}, u>:$ > r(u,v,w)

$$\begin{bmatrix} v \ u^2 \cos(w) \\ v \ u^2 \sin(w) \\ u \end{bmatrix}$$
(3.1)

where $u \in [0; 1]$, $v \in [0; 1]$ and $w \in [0; \frac{\pi}{2}]$ (see the figure in the question text).

Question 1 > M:=<diff(r(u,v,w),u) |diff(r(u,v,w),v)|diff(r(u,v,w),w)> $M := \begin{bmatrix} 2 v u \cos(w) & u^{2} \cos(w) & -v u^{2} \sin(w) \\ 2 v u \sin(w) & u^{2} \sin(w) & v u^{2} \cos(w) \\ 1 & 0 & 0 \end{bmatrix}$ (3.1.1)

> Jr:=simplify(Determinant(M))

$$Jr := u^4 v \tag{3.1.2}$$

which is greater than or equal to zero since $v \ge 0$. The corresponding Jacobian is thus

> Jacobian:=Jr

$$Jacobian \coloneqq u^4 v \tag{3.1.3}$$

Question 2

We consider the vector field > $\forall := (x, y, z) \rightarrow \langle x + exp(y \ast z), 2 \ast y - exp(x \ast z), 3 \ast z + exp(x \ast y) \rangle :$ > $\forall (x, y, z)$ $\begin{bmatrix} x + e^{yz} \\ 2y - e^{xz} \\ 3z + e^{yx} \end{bmatrix}$

 ∂L is the closed surface of L with an orientation according to outwards-pointing unit normal vector. From the Gauss Divergence Theorem we then get

Flux(
$$\mathbf{V}, \partial L$$
) = $\int_{L} \text{Div}(\mathbf{V}) \, \mathrm{d}\boldsymbol{\mu} = \int_{0}^{\frac{\pi}{2}} \int_{0}^{1} \int_{0}^{1} \text{Div}(\mathbf{V}) (\mathbf{r}(u, v, w)) \text{Jacobian}(u, v, w) \, \mathrm{d}u \, \mathrm{d}v \, \mathrm{d}w$

> div:=V->VectorCalculus[Divergence](V):

> DivV:=div(V)(x,y,z)

$$DivV \coloneqq 6 \tag{3.2.2}$$

(3.2.1)

> integrand:=DivV*Jacobian

$$integrand := 6 u^4 v \tag{3.2.3}$$

> Int(integrand, [u=0..1,v=0..1,w=0..Pi/2])=int(integrand, [u=0..1,v= 0..1,w=0..Pi/2])

$$\int_{0}^{\frac{\pi}{2}} \int_{0}^{1} \int_{0}^{1} 6 u^{4} v \, du \, dv \, dw = \frac{3\pi}{10}$$
(3.2.4)

Question 3

A parametric representation of a profile area *F* in the (x, z) plane which forms the solid body *L* according to the description in the question text is achieved by setting w = 0 in the given parametric representation of *L*.

```
> s:=(u,v)-><v*u^2,0,u>:
> s(u,v)
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\begin{bmatrix} v u^2 \\ 0 \\ u \end{bmatrix} (3.3.1)
```

```
where u∈[0; 1] and v∈[0; 1].
> plot3d(s(u,v),u=0..1,v=0..1,scaling=constrained,axes=normal,view=
    0..1,orientation=[-120,70],color=yellow)
```



Problem 4

```
> restart:with(plots):with(LinearAlgebra):
    prik:=(x,y)->VectorCalculus[DotProduct](x,y):
    vop:=proc(X)op(convert(X,list))end proc:
```

Let *a* be a positive real number. A flowcurve *K* of a smooth vector field \mathbf{V} in (x, y, z) space is given by the parametric representation

> r:=t-><exp(-t),cos(t)-sin(t),cos(t)+sin(t)>:
> r(t)

$$\begin{array}{c} e^{-t} \\ \cos(t) - \sin(t) \\ \cos(t) + \sin(t) \end{array}$$
(4.1)

where $t \in [0; a]$.

Question 1

The corresponding Jacobian is > Jacobian:=simplify(sqrt(prik(diff(r(t),t),diff(r(t),t)))) $I_{resolview} := \sqrt{e^{-2t} + 2}$ (41)

$$Jacobian := \sqrt{e^{-2t} + 2}$$
(4.1.1)

which means that m = 2 and n = 2.

Question 2

Since *K* is a flow curve for the vector field **V**, then we have the relationship $\mathbf{V}(\mathbf{r}(t)) = \mathbf{r}'(t)$ for all $t \in [0; a]$. From this it follows that

$$\operatorname{Tan}(\mathbf{V}, K) = \int_{K} \mathbf{V} \cdot \mathbf{e} \, \mathrm{d}\mu = \int_{0}^{a} \mathbf{V}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) \, \mathrm{d}t = \int_{0}^{a} \mathbf{r}'(t) \cdot \mathbf{r}'(t) \, \mathrm{d}t = \int_{0}^{a} (\operatorname{Jacobian}(t))^{2} \, \mathrm{d}t \, .$$

Question 3

>

Let a = 5, and then we can calculate

> Tan:=Int(Jacobian²,t=0..5)=int(Jacobian²,t=0..5)

$$Tan := \int_0^5 \left(e^{-2t} + 2 \right) dt = \frac{21}{2} - \frac{e^{-10}}{2}$$
(4.3.1)

- > curve:=spacecurve(r(t),t=0..5,color=red,axes=normal): pnt:=pointplot3d([[1,1,1],[vop(r(5))]],symbol=solidcircle, symbolsize=15):

